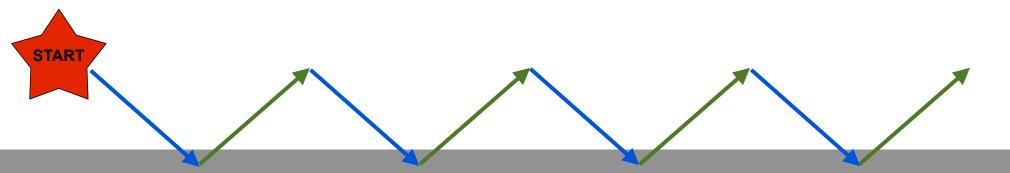


#### LINE FOLLOWING





# Theory of Operation



#### **Motor Actions**

turn turn turn turn turn turn turn turn **RIGHT** LEFT **RIGHT** LEFT **RIGHT** LEFT **RIGHT** LEFT

#### **Light sensor**

dark light dark light dark



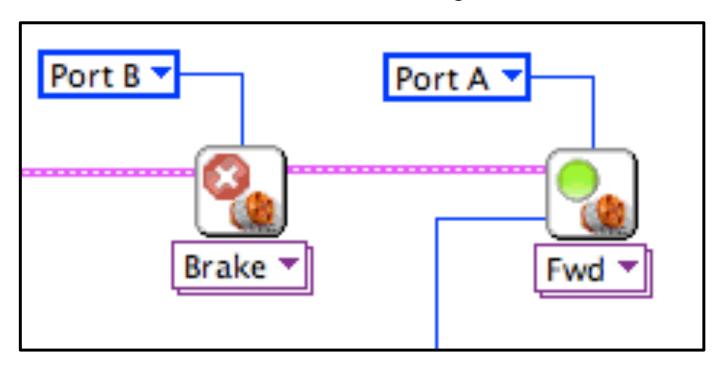
#### How Do We Do This?

- 1. If the light sensor is "light"
  - Turn Right
- 2. Else if the light sensor is "dark"
  - Turn Left



## Turning

The left motor is A and the right motor is B

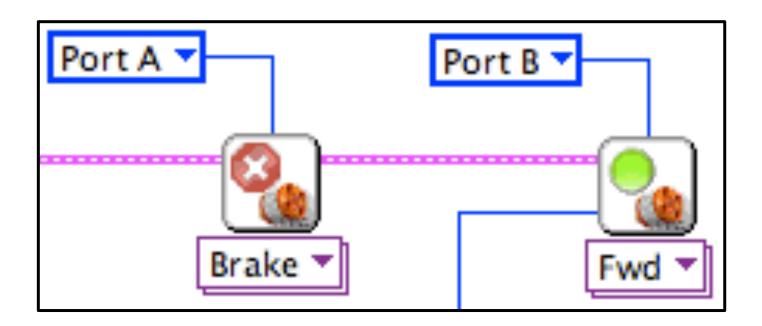


Which way does this turn?



## Turning

The left motor is A and the right motor is B

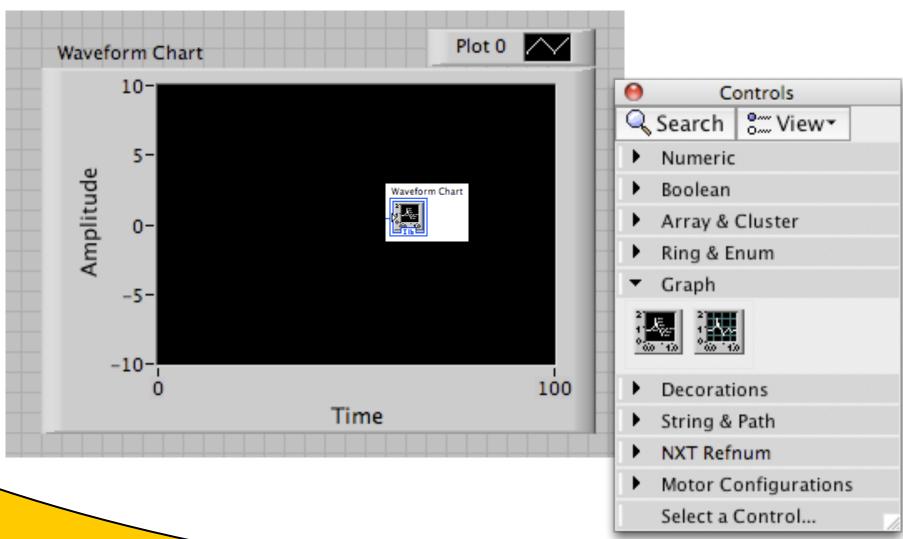


Which way does this turn?

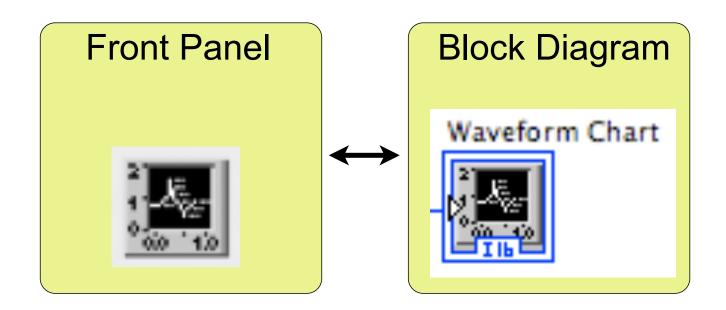


Do an experiment in LabVIEW

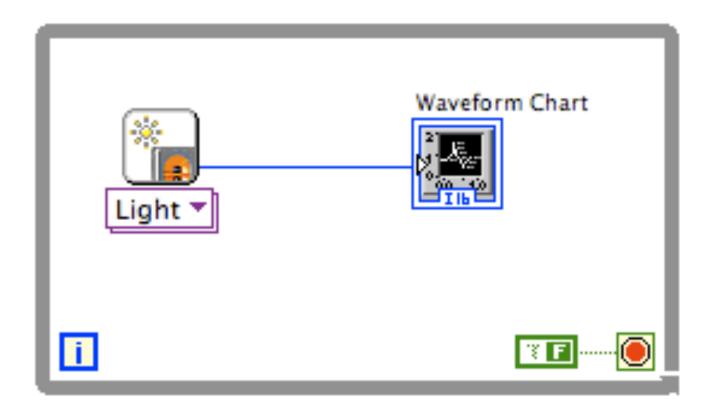










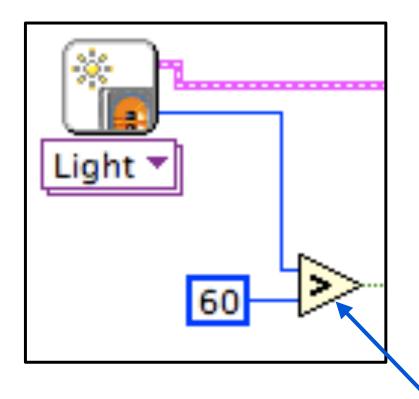




Lots of Noise pick a threshold



## Thresholding

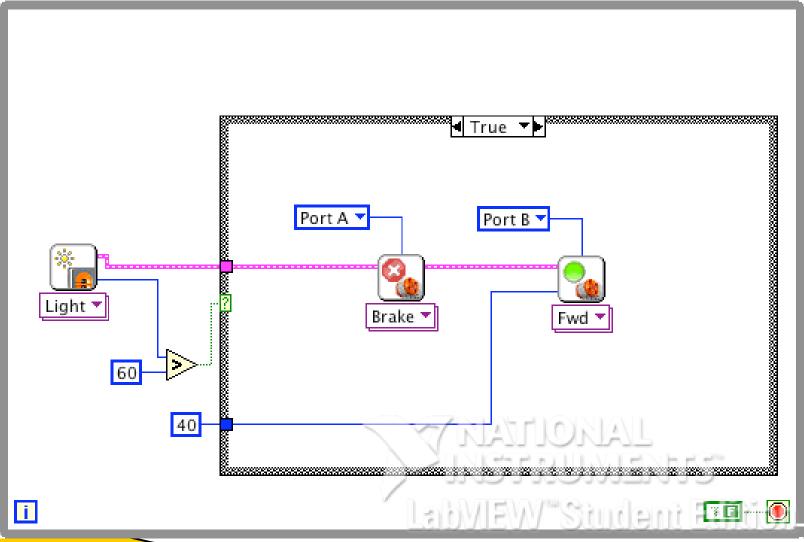


If the light is **greater than** 60 Emit **true** 

Greater than



# Putting it all Together





# Putting it all Together

