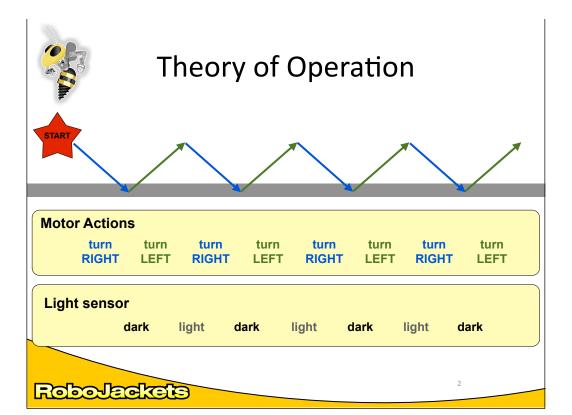


LINE FOLLOWING

RoboJackets





How Do We Do This?

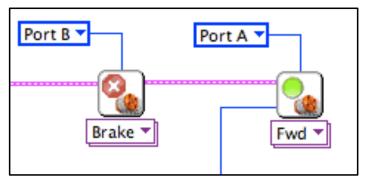
- 1. If the light sensor is "light"
 - Turn Right
- 2. Else if the light sensor is "dark"
 - Turn Left

RoboJackets



Turning

The left motor is A and the right motor is B



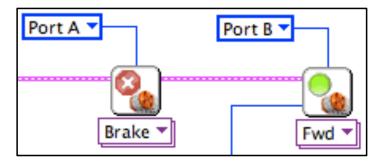
Which way does this turn?





Turning

The left motor is A and the right motor is B



Which way does this turn?

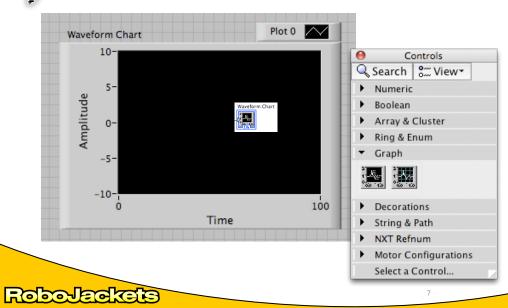




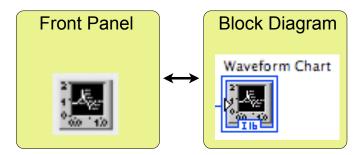
Do an experiment in LabVIEW

RoboJackets



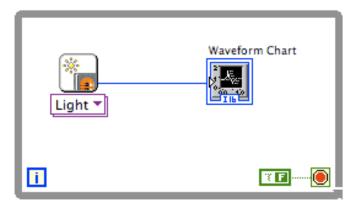






RoboJackets





RoboJackets



Lots of Noise pick a threshold

RoboJackets

